

Asteroid Mobility Using Screw-Powered Vehicles (SPV's)

Sierra Ramirez

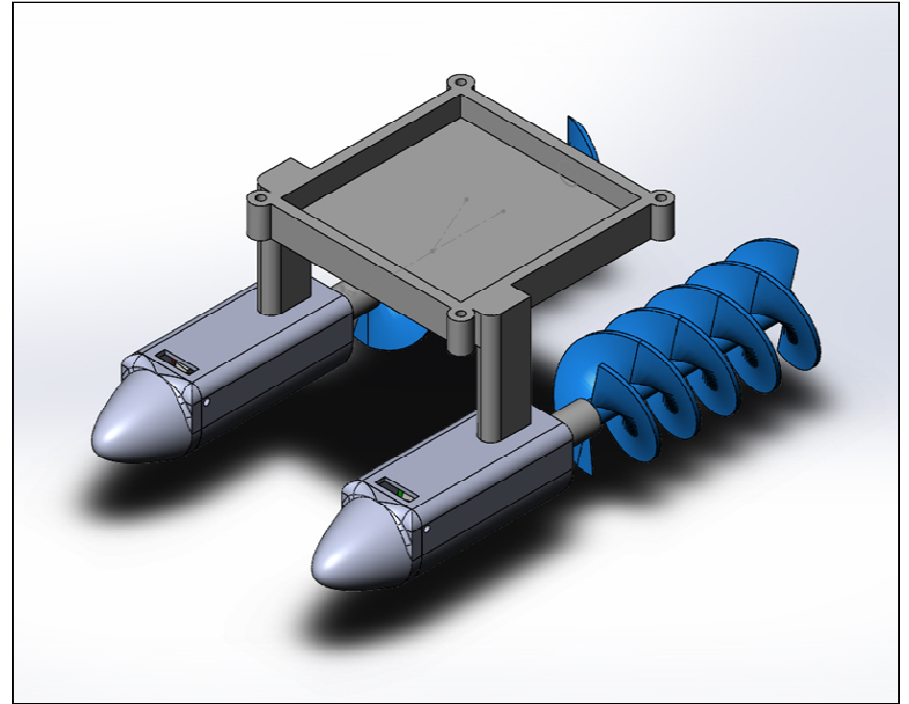
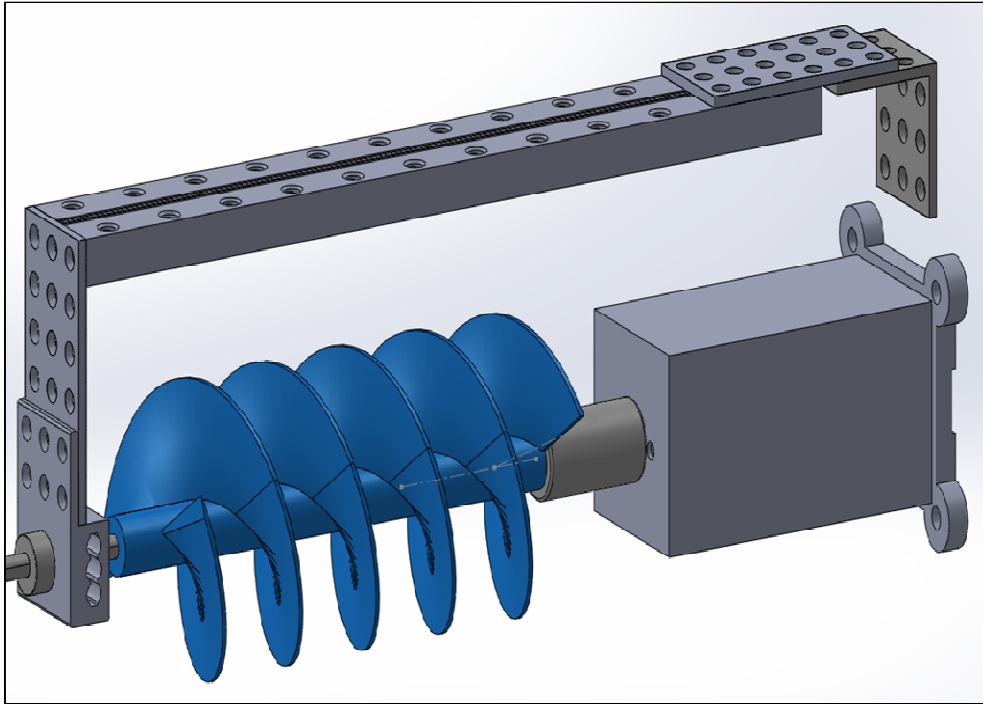
Mentor: Hamid Marvi

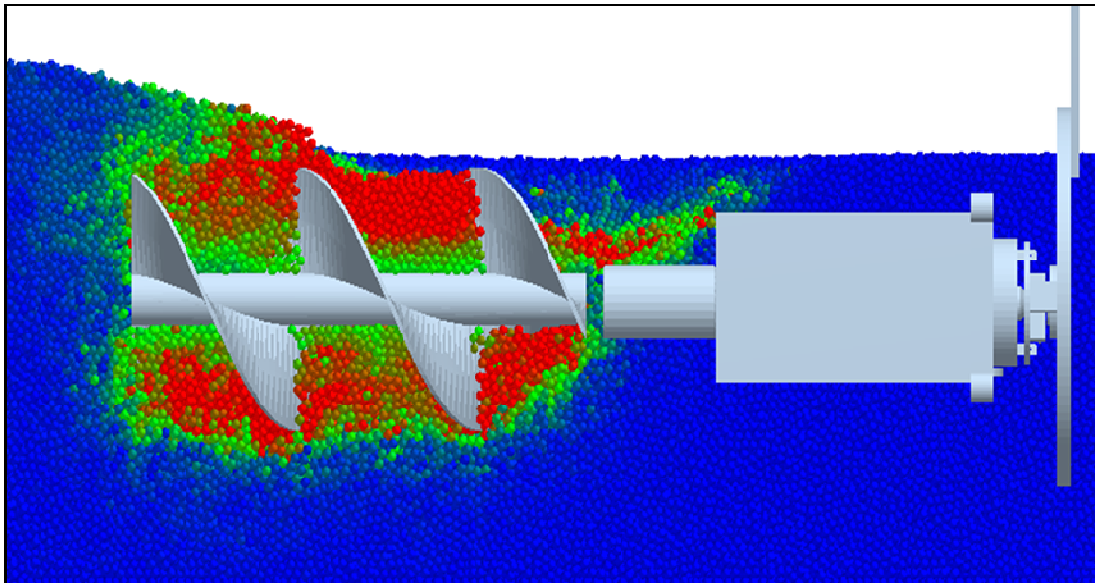
School for Engineering of Matter, Transport
and Energy
Arizona State University

Motivation: Why SPV's?

- SPV's are used for transportation on different terrestrial applications such as mud, snow, clay, and amphibious environments
- A gap remains in reimagining SPV transport for off-Earth environments and characterizing design aspects
- Goal: use experimental results to validate simulations for further research and studying the characteristics of how SPV's move and generate forces in granular environments

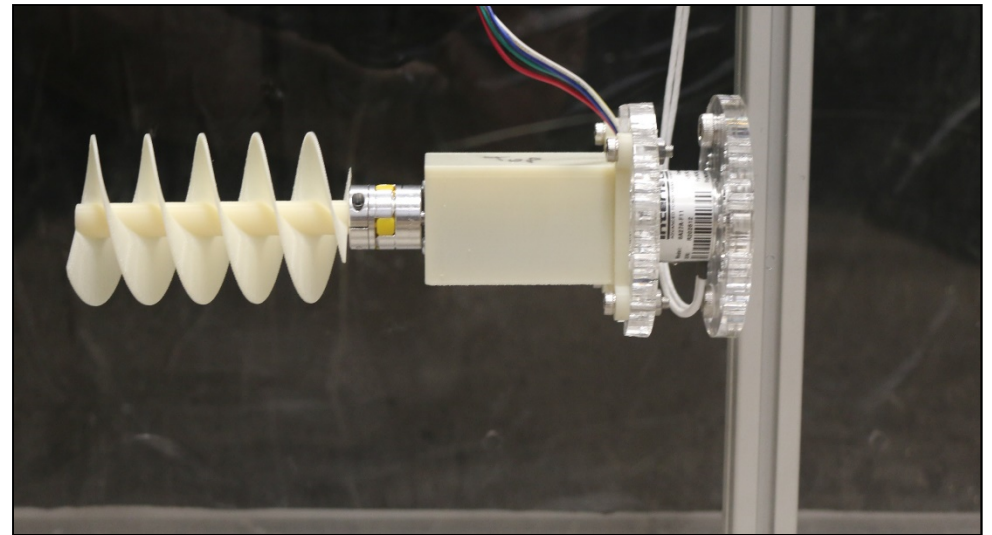
3D Model Designs



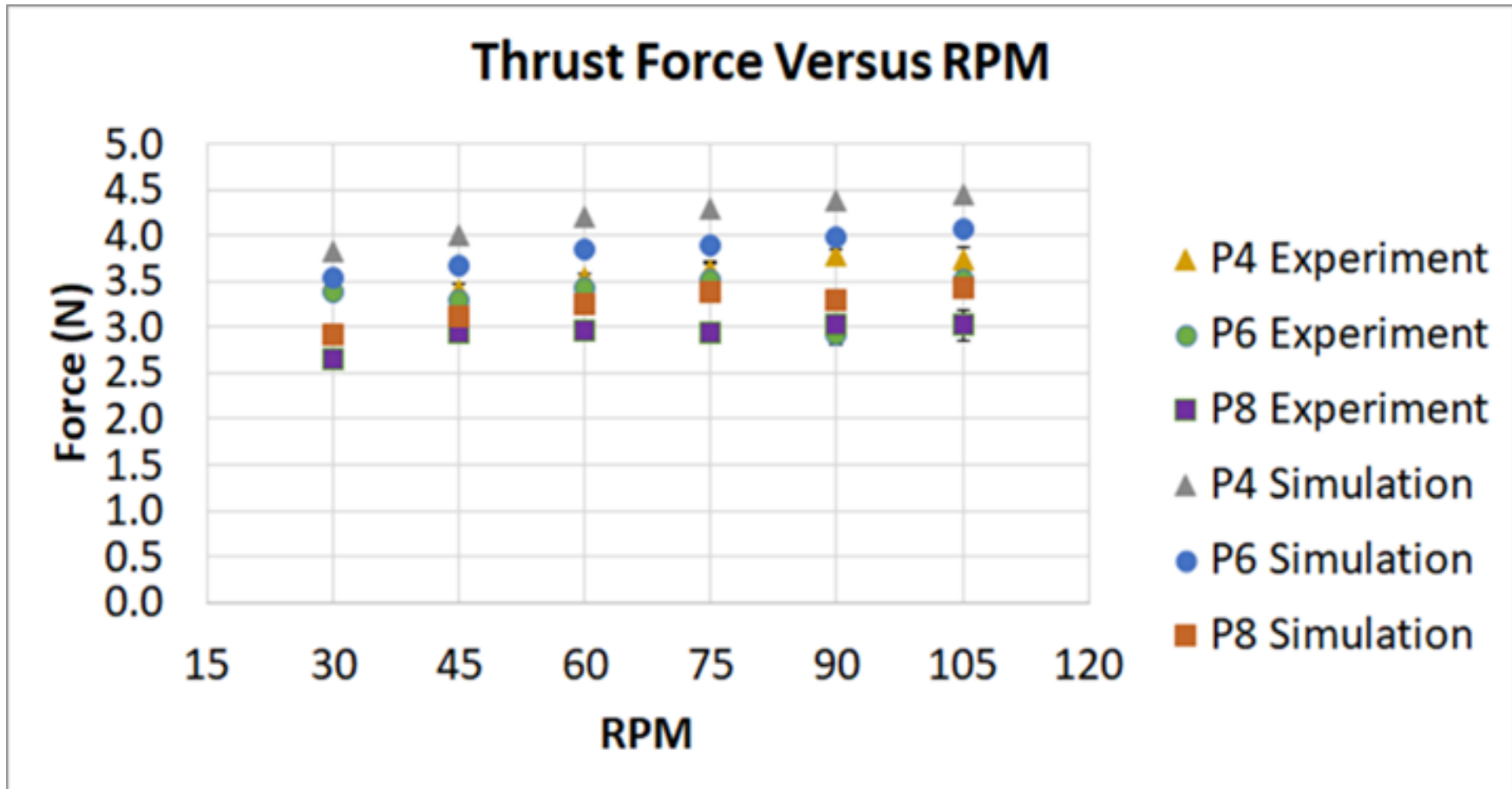


- EDEM software was used for static testing
- EDEM and ADAMS software was used for dynamic testing
- Particle size used: 2mm with a normal distribution with STDEV of 0.1mm and 1.1 aspect ratio

- Three 3D printed ABS screws with different diameter pitches
- Used a 12V Pololu motor driven by an Arduino Uno
- Experimental bed contained soda-lime glass beads

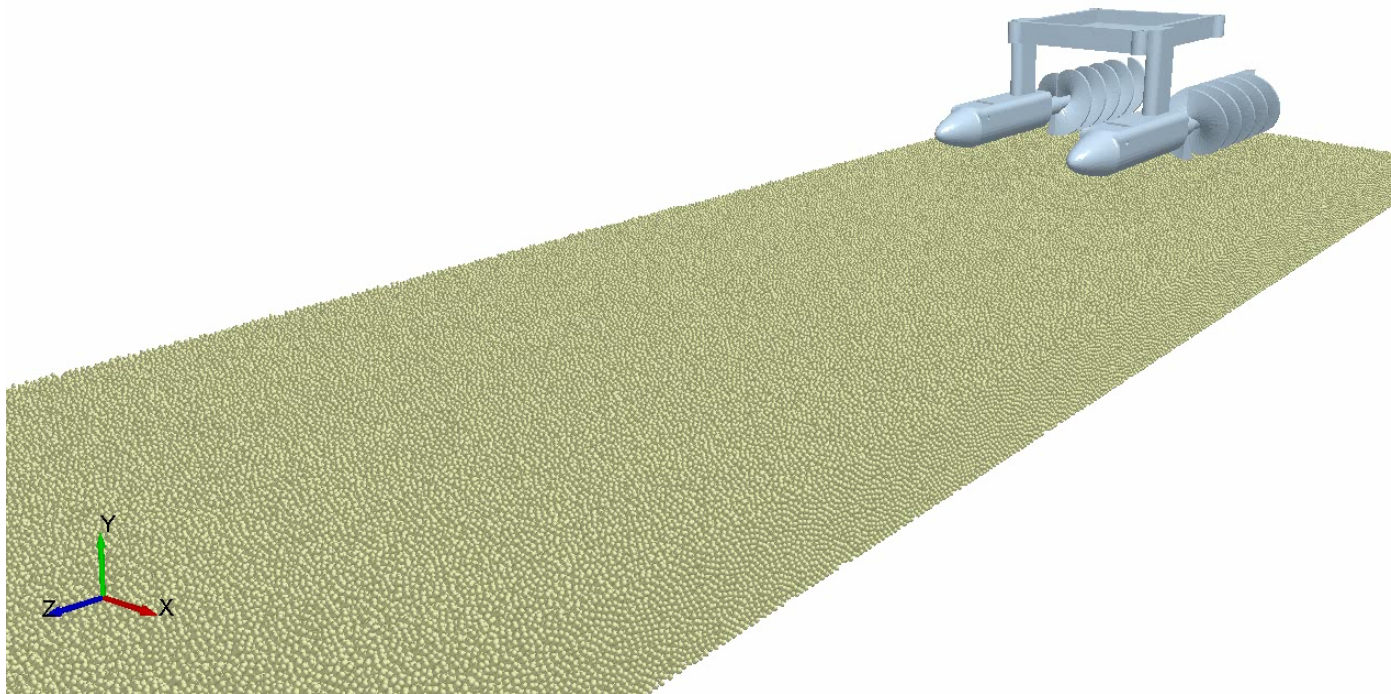


Simulations vs. Experiments

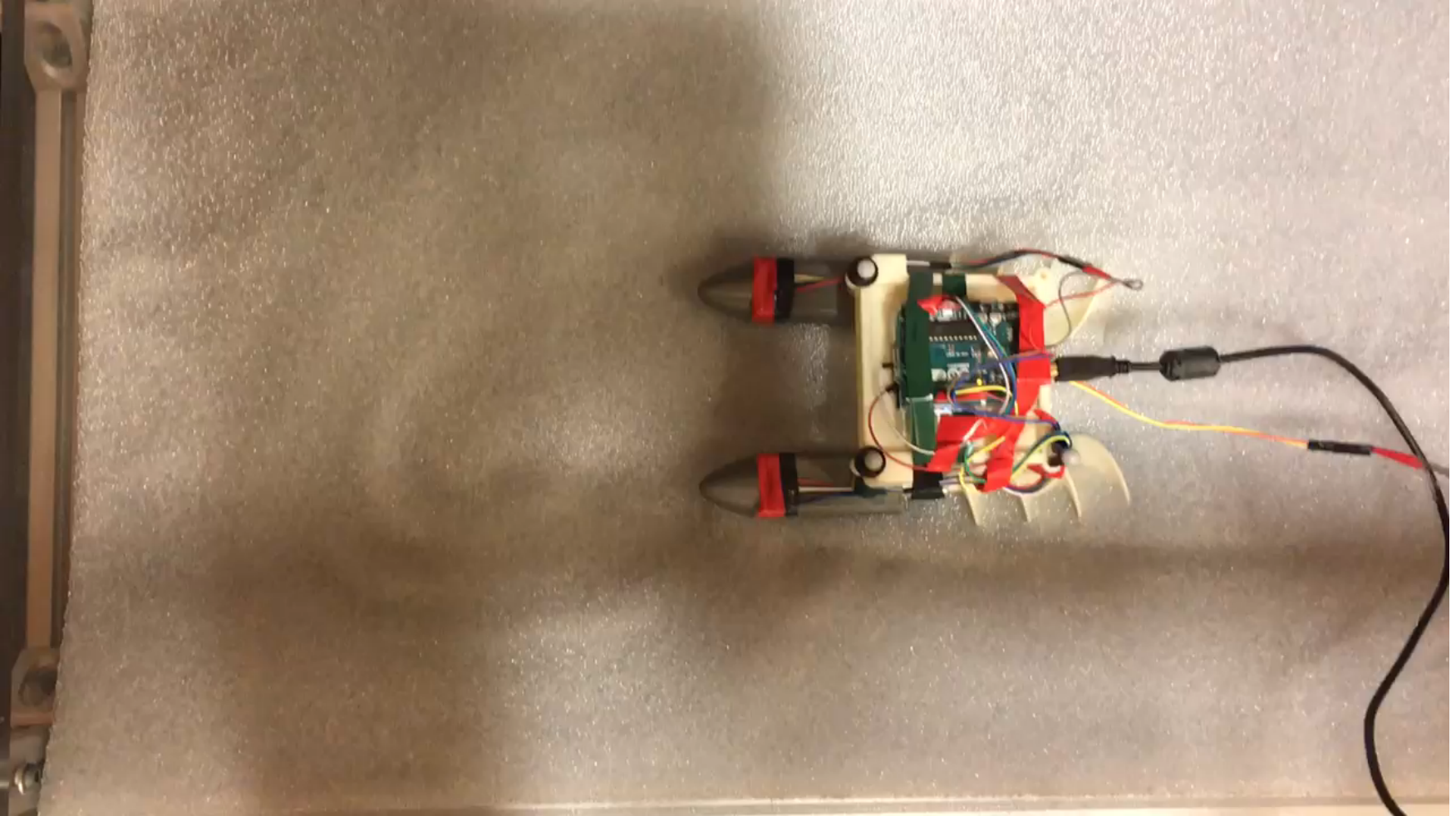


- Use current design and results of full body to assist in optimization

Time: 0 s
EDEM™
Academic



Future Work



Acknowledgements

Thank you ASU/NASA Space Grant for providing me with the opportunity to further my research. In addition, thank you to my professor Hamidreza Marvi for mentoring me throughout the course of this project. Also, special thanks to my Asteroid Mobility team members – Andrew Thoesen and Teresa McBryan!